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API based on UDP protocol, 1339/UDP port is used for communication.

**Action:** Get controller f/w version
**Command:** “ver” (hex: 76:65:72)
**Answer:** “ISSI LC-2=1x.y (s/n:150xx)”

**Action:** Change controller IP address to 192.168.1.2
**Command:** “ChangelP=192.168.1.2”
**Answer:** no answer, controller will set IP and restart

**Action:** Initialize lens, and get current motors values and ranges (aperture ranges would change when zoom changed)
**Command:** “ping” (hex: 70:69:6e:67)
**Answer:** contains 7 packets:
  #1 “zRange=minX,maX”
  where minX– minimum zoom value, maxX – maximum zoom value
  #2 “fRange=minZ,maxZ”
  where minY– minimum focus value, maxY – maximum focus value
  #3 “aRange=minY,maxY”
  where minZ– minimum aperture value, maxZ – maximum aperture value
  #4 “Current=XX,YY,ZZ”
  where XX– current zoom value, YY– current focus value, ZZ- current aperture value
  #5 “AF=X”
  where X =1 if AF selected on lens and 0 if MF selected.
  #6 “IS=X”
  where X=1 if Image Stabilization(IS) switch is enabled, 0 if disabled or lens have no IS
  #7 “ISactive=X”
  where X=1 if IS is activated and 0 if it deactivated
  “nolensfound” - in case no lens found

**Action:** Move Focus motor on X units
**Command:** “moveFocus=X”
where X could be as positive as negative values.
**Answer:** “Focus=Y”, where Y – current value of Focus motor
or “errorFocus” when focus value is not reachable;

**Action:** Move Aperture motor on X step (one-quarter-stop f-number)
**Command:** “moveAper=X”
where X could be as positive as negative values.
**Answer:** “Iris=Y”, where Y – current value of Aperture
or “errorAper” (in old f/w) and “errorAperLimits” when aperture value is not reachable
Action: Set desired value for Focus motor
Command: “setFocus=X”
where X is positive value
Answer: Focus =XXX, where XXX is the current value, and next packet “focusDone” - indicate that desired focus is set (for non USM lens could take more time)

Action: Set desired value for aperture (in f-number)
Command: “setAper=X”
where X is in quarter-stop f-number scale, please use pre-calculated f-stop numbers: [1.0, 1.1, 1.2, 1.3, 1.4, 1.5, 1.7, 1.8, 2.0, 2.2, 2.4, 2.6, 2.8, 3.1, 3.4, 3.7, 4.0, 4.4, 4.8, 5.2, 5.6, 6.2, 6.7, 7.3, 8.0, 8.7, 9.5, 10.4, 11.3, 12.3, 13.5, 14.7, 16, 17.4, 19, 20.7, 22.6, 24.7, 26.9, 29.3, 32.0, 34.9, 38.1, 41.5, 45.3, 49.4, 53.8, 58.7] for firmware 1.7.3 and earlier, and [1.0, 1.1, 1.3, 1.4, 1.6, 1.8, 2.0, 2.2, 2.5, 2.8, 3.2, 3.5, 4.0, 4.5, 5.0, 5.6, 6.3, 7.1, 8.0, 9.0, 10, 11, 13, 14, 16, 18, 20, 22, 25, 29, 32, 36, 40, 45, 51, 57, 64, 72, 80, 90] for f/w versions after 1.7.4.
Answer: “Iris=Y”, where Y – current value of Aperture, if X is out of range will answer with “errorAper-Limits” message

Action: detect IS (Image Stabilization) availability
Command: “isIS”
Answer: “IS=Y”
where Y could be 0 or 1, “0” - means lens does not have IS function, “1” - lens have IS function. Also will answer “0” if IS switch is in OFF position.

Action: activate IS (Image Stabilization) function
Command: “enableIS=X”
Answer: “ISactive=Y”
where X is the amount of seconds to keep IS active, from [0-3600]. “0” - disable IS, and Y is 0 or 1 - current IS status

Action: Set nickname for LC (stored in LC memory)
Command: “setNAME=XXXXXXX”
where XXXXXXX is 7-symbols name for this controller.
Answer: no answer

Action: Get LC nickname (stored in LC memory)
Command: “getName”
Answer: “NAME=XXXXXX”

Action: soft restart LC-2
Answer: OK

Action: hard restart LC-2
Answer: OK
**Action:** explore focus limits  
**Command:** “refRange”  
**Answer:** “fRange=minY,maxY”  
where minY – minimum focus value, maxY – maximum focus value

**Action:** get lens name  
**Command:** “getLens”  
**Answer:** “Lens=XXX”, where XXX is the lens name stored in internal lens memory, lens should support this command.

**Action:** alternative way to set lens focus, lens will move focus motor to minimum position, reset encoder counter and then position the focus. Helps to suppress accumulative lens drift effect for some lens.  
**Command:** “setFocus2=X”  
where X is positive value  
**Answer:** Focus =XXX, where XXX is the current value, and next packet “focusDone” - indicate that desired focus is set (for non USM lens could take more time)

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### PERL EXAMPLE SCRIPT – SEND COMMAND

```perl
#!/usr/bin/perl -w
use IO::Socket;
use strict;
my $sock = IO::Socket::INET->new(
  Proto => 'udp',
  PeerPort => 1339,
  PeerAddr => '192.168.2.252',
) or die "Could not create socket: $!

my $size = $sock->send($ARGV[0]) or die "Send error: $!

print "$size bytes sent

my $response = 

$sock->recv( $response, 1024 );
print "Response: $response";

$sock->close();
```

Usage: ./udpsend.pl setFocus=1000  
will send command “setFocus=1000” to 192.168.2.252 to port 1339/UDP

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### PYTHON EXAMPLE SCRIPT – SEND COMMAND

```python
import socket
UDP_IP = "192.168.2.252"
UDP_PORT = 1339
print ("ISSI :: Canon Pyhton Script Example\n")
MESSAGE = "setFocus=1000"
sock = socket.socket(socket.AF_INET, socket.SOCK_DGRAM) # UDP
sock.sendto(MESSAGE.encode(), (UDP_IP, UDP_PORT))
try:
  while True:
    data, addr = sock.recvfrom(1024)
    if not data: break
    print ("Received: ", data)
except socket.error:
  print("*")
sock.close()
```

Usage: ./udpsend.py  
will send command “setFocus=1000” to 192.168.2.252 to port 1339/UDP

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